

Title Of The Thesis

John Student  
Field of study  
Academic year 2016/2017

Supervisor: prof. dr hab. inż. Stefan The Greatest Advisor

1. Introduction

This template provides authors with most of the formatting specifications needed for preparing electronic versions of their diploma posters. Margins, column widths, and type styles are built-in. Examples of the styles are provided throughout this document.

The main text fonts used in this poster are Source Sans Pro (delivered together with this template). The main text should be single-spaced and justified. Use 12 point font for this text. Use 17 point font for your headers. Set 8 points of space before and after each header.

The equations – if they appear in the text – should be centered and may be numbered consecutively. Figure captions should be placed below the figures. Use 11 point font for your figure titles. Table heads should appear above the tables. Use 11 point font for your table titles.

2. Introductory analysis

Example of a block

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Praesent sed lorem hendrerit, congue ex sit amet, lobortis nibh. Pellentesque suscipit enim ac varius sodales.

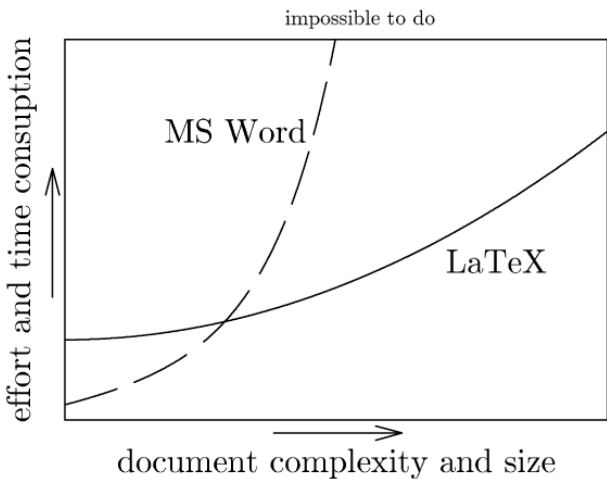


Figure: My effort associated with thesis preparation

3. Other results

$$y(t) = \mathcal{L}^{-1}[Y(s)] = 1 - \frac{e^{-\sigma t}}{\sqrt{1 - \xi^2}} \sin \left( \omega_d t + \arctan \frac{\sqrt{1 - \xi^2}}{\xi} \right) \tag{1}$$

Table: Selected Historical Developments of Control Systems

Date	Development
...	...
1927	Black, Feedback electronic amplifier
1932	Nyquist, Nyquist stability criterion
1936	Callender, PID controller
1938	Bode, Frequency response methods
1942	Wiener, Optimal filter design, Ziegler-Nichols PID rules
1947	Nichols, Nichols charts
1948	Evans, Root locus
1950	Kochenberger, Nonlinear analysis
1956	Pontryagin, Maximum principle
1957	Bellman, Dynamic programming
1960	Draper, Inertial navigation; Kalman, Optimal estimation
...	...

Title of this note

Short summary and one small conclusion.

4. Gauss principle

$$\min_{\ddot{\mathbf{q}}} \mathcal{G}(\ddot{\mathbf{q}}) \quad \text{p.o.} \quad \ddot{\Phi} = \mathbf{0}$$

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Ut purus elit, vestibulum ut, placerat ac, adipiscing vitae, felis. Curabitur dictum gravida mauris. Nam arcu libero, nonummy eget, consectetur id, vulputate a, magna. Donec vehicula augue eu neque. Pellentesque habitant morbi tristique senectus et netus et malesuada fames ac turpis egestas. Mauris ut leo. Cras viverra metus rhoncus sem. Nulla et lectus vestibulum urna fringilla ultrices. Phasellus eu tellus sit amet tortor gravida placerat. Integer sapien est, iaculis in, pretium quis, viverra ac, nunc. Praesent eget sem vel leo ultrices bibendum. Aenean faucibus. Morbi dolor nulla, malesuada eu, pulvinar at, mollis ac, nulla. Curabitur auctor semper nulla. Donec varius orci eget risus. Duis nibh mi, congue eu, accumsan eleifend, sagittis quis, diam. Duis eget orci sit amet orci dignissim rutrum.

5. Conclusions

- First item
- Second item
- I cannot deal with it...